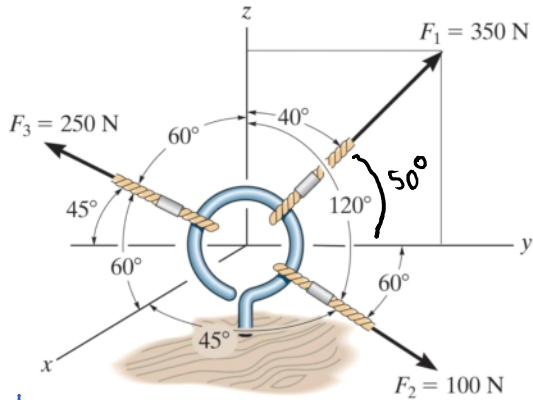


Example



Note that the angles do not all lie in the same plane!

The cables attached to the screw eye are subjected to the three forces shown.

- Express each force vector using the Cartesian vector form (components form).
- Determine the magnitude of the resultant force vector
- Determine the direction cosines of the resultant force vector

a) Start with \vec{F}_1

$$\vec{F}_1 = 0 \cdot \hat{i} + F_{1y} \hat{j} + F_{1z} \hat{k}$$

$$= F_1 \left(0 \cdot \hat{i} + \frac{F_{1y}}{F_1} \hat{j} + \frac{F_{1z}}{F_1} \hat{k} \right)$$

$$= F_1 \left(\cos(50^\circ) \hat{j} + \cos(40^\circ) \hat{k} \right)$$

$$= (350 \text{ N}) (\cos 50^\circ \hat{j} + \cos 40^\circ \hat{k})$$

$$= (\underline{225} \hat{j} + \underline{268} \hat{k}) \text{ N}$$

$$\vec{F}_2 = F_2 \cdot (\cos 45^\circ \hat{i} + \cos 60^\circ \hat{j} + \cos 120^\circ \hat{k})$$

$$= (100 \text{ N}) \left(\frac{\sqrt{2}}{2} \hat{i} + \frac{1}{2} \hat{j} - \frac{1}{2} \hat{k} \right)$$

$$= (\underline{70.7} \hat{i} + \underline{50} \hat{j} - \underline{50} \hat{k}) \text{ N}$$

$$\vec{F}_3 = F_3 \cdot (\cos 60^\circ \hat{i} + \cos 135^\circ \hat{j} + \cos 60^\circ \hat{k})$$

$$= (\underline{125} \hat{i} - \underline{177} \hat{j} + \underline{125} \hat{k}) \text{ N}$$

b) Resultant force: $\Sigma \vec{F} = \vec{F}_1 + \vec{F}_2 + \vec{F}_3$

in \hat{i} direction: $\Sigma F_x = (0 + 70.7 + 125) N \cdot \hat{i} = 196 N \hat{i}$

in \hat{j} direction: $\Sigma F_y = (225 + 50 - 177) N \cdot \hat{j}$
 $= 98 N \hat{j}$

in \hat{k} direction: $\Sigma F_z = (268 - 50 + 125) N \hat{k}$
 $= 343 N \hat{k}$

$$\Sigma \vec{F} = (196 \hat{i} + 98 \hat{j} + 343 \hat{k}) N$$

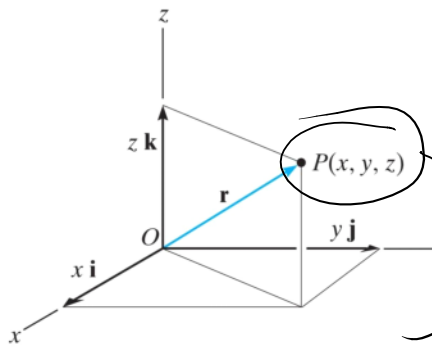
$$|\Sigma \vec{F}| = \sqrt{(196)^2 + (98)^2 + (343)^2} N = 407 N$$

c) Direction cosines of $\Sigma \vec{F}$:

$$\frac{\Sigma \vec{F}}{|\Sigma \vec{F}|} = \frac{196}{407} \hat{i} + \frac{98}{407} \hat{j} + \frac{343}{407} \hat{k}$$

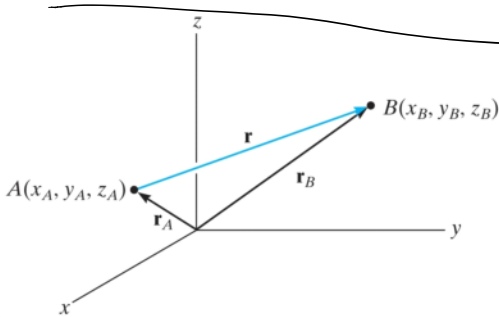
$$= 0.481 \hat{i} + 0.241 \hat{j} + 0.843 \hat{k}$$

Position vectors



A position vector \underline{r} is a fixed vector that locates a point in space relative to another point

here, $\underline{r} = x\hat{i} + y\hat{j} + z\hat{k}$ give point $P(x, y, z)$ relative to the origin.
(might write as $\underline{r} = \underline{r}_{OP}$)



\underline{r} is position of B relative to A

$$\underline{r}_A + \underline{r} = \underline{r}_B$$

$$\Rightarrow \underline{r} = \underline{r}_B - \underline{r}_A$$

$$= (x_B - x_A)\hat{i} + (y_B - y_A)\hat{j} + (z_B - z_A)\hat{k}$$

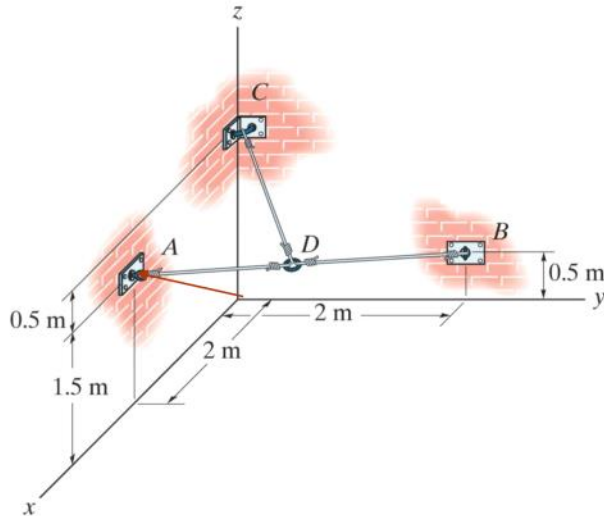
(might write \underline{r} as \underline{r}_{AB})

$$\underline{r}_{AB} = \underline{r}_B - \underline{r}_A$$

$$= \underline{r}_{OB} - \underline{r}_{OA}$$

Example

The ring at D is midway between points A and B . Determine the lengths of wires AD , BD and CD



Dis midway between A & B :

$$X_D = \frac{X_A + X_B}{2} = \frac{(2+0)\text{ m}}{2} = 1\text{ m}$$

$$Y_D = \frac{Y_A + Y_B}{2} = \frac{(0+2)\text{ m}}{2} = 1\text{ m}$$

$$Z_D = \frac{Z_A + Z_B}{2} = \frac{(1.5+0.5)\text{ m}}{2} = 1\text{ m}$$

$$\Rightarrow \underline{r}_{OD} = (1\text{ m})(\hat{i} + \hat{j} + \hat{k})$$

$$\underline{r}_{OA} = (2\hat{i} + 0\hat{j} + 1.5\hat{k})\text{ m}$$

$$\underline{r}_{OA} + \underline{r}_{AD} = \underline{r}_{OD} \Rightarrow \underline{r}_{AD} = \underline{r}_{OD} - \underline{r}_{OA} = [(1-2)\hat{i} + (1-0)\hat{j} + (1-1.5)\hat{k}]\text{ m}$$

$$= [-1\hat{i} + 1\hat{j} - 0.5\hat{k}]\text{ m}$$

$$\underline{r}_{BD} = \underline{r}_{OD} - \underline{r}_{OB} = [(1-0)\hat{i} + (1-2)\hat{j} + (1-0.5)\hat{k}]\text{ m}$$

$$= (1\hat{i} - 1\hat{j} + 0.5\hat{k})\text{ m}$$

$$\underline{r}_{CD} = \underline{r}_{OD} - \underline{r}_{OC} = [(1-0)\hat{i} + (1-0)\hat{j} + (1-2)\hat{k}]\text{ m}$$

$$= (1\hat{i} + 1\hat{j} - 1\hat{k})\text{ m}$$

Cable lengths are the magnitudes of the position vectors:

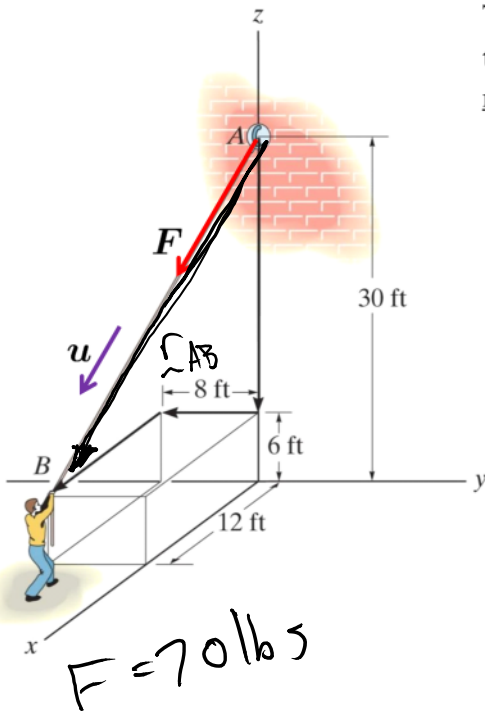
$$r_{AD} = \sqrt{(-1\text{m})^2 + (1\text{m})^2 + (-0.5\text{m})^2} = 1.50\text{m}$$

$$r_{BD} = \sqrt{(1\text{m})^2 + (-1\text{m})^2 + (0.5\text{m})^2} = 1.50\text{m}$$

$$r_{CD} = \sqrt{(1\text{m})^2 + (1\text{m})^2 + (-1\text{m})^2} \text{m} = 1.73\text{m}$$

Force vector directed along a line

The force vector \mathbf{F} acting along the rope can be defined by the unit vector \mathbf{u} (defined the direction of the rope) and the magnitude of the force.



$$\mathbf{F} = F \cdot \hat{\mathbf{u}}$$

vector magnitude

unit vector in the direction of the rope

$$\hat{\mathbf{u}} = \frac{\mathbf{r}}{|\mathbf{r}|} = \frac{\mathbf{r}}{r}$$

$$\mathbf{r}_{AB} = (\mathbf{r}_B - \mathbf{r}_A) = (x_B - x_A)\hat{i} + (y_B - y_A)\hat{j} + (z_B - z_A)\hat{k}$$

$$= (12\hat{i} - 8\hat{j} - 24\hat{k}) \text{ ft}$$

$$\text{length} = \sqrt{(12 \text{ ft})^2 + (-8 \text{ ft})^2 + (-24 \text{ ft})^2}$$

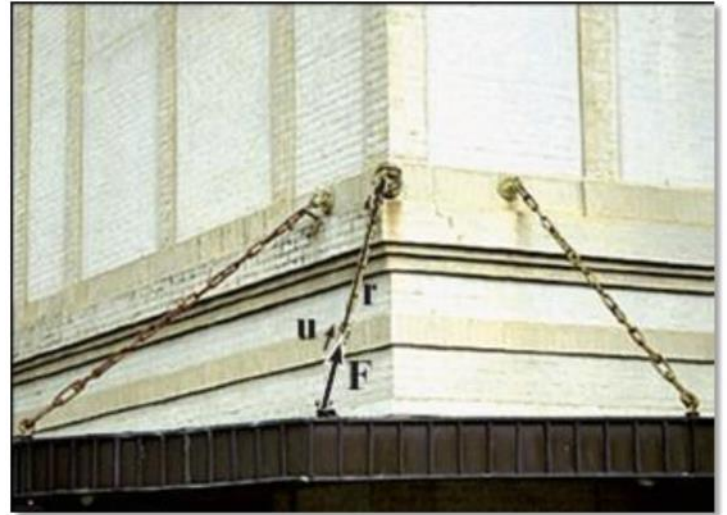
$$= 28 \text{ ft}$$

$$\hat{\mathbf{u}} = \frac{12}{28}\hat{i} - \frac{8}{28}\hat{j} - \frac{24}{28}\hat{k}$$

$$\mathbf{F} = F \cdot \hat{\mathbf{u}} = (70 \text{ lbs}) \hat{\mathbf{u}}$$

$$= (30\hat{i} - 20\hat{j} - 60\hat{k}) \text{ lbs}$$

Force vector directed along a line

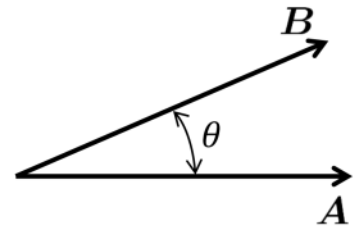


Don't look up!

Dot (or scalar) product

The dot product of vectors **A** and **B** is defined as such

$$\mathbf{A} \cdot \mathbf{B} = |\mathbf{A}| |\mathbf{B}| \cos(\theta)$$



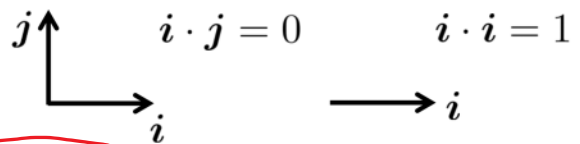
Laws of operation:

$$\mathbf{A} \cdot \mathbf{B} = \mathbf{B} \cdot \mathbf{A}$$

$$\alpha(\mathbf{A} \cdot \mathbf{B}) = \alpha\mathbf{A} \cdot \mathbf{B} = \mathbf{A} \cdot \alpha\mathbf{B}$$

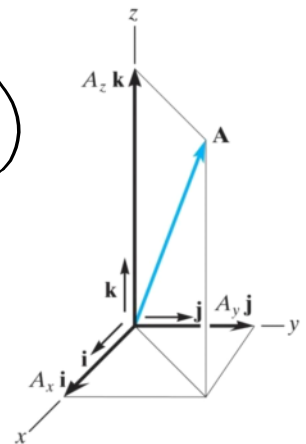
$$\mathbf{A} \cdot (\mathbf{B} + \mathbf{C}) = \mathbf{A} \cdot \mathbf{B} + \mathbf{A} \cdot \mathbf{C}$$

Note that:



Cartesian vector formulation:

$$\mathbf{A} \cdot \mathbf{B} = (A_x \hat{i} + A_y \hat{j} + A_z \hat{k}) \cdot (B_x \hat{i} + B_y \hat{j} + B_z \hat{k})$$



$$\begin{aligned} &= A_x B_x \hat{i} \cdot \hat{i} + A_x B_y \hat{i} \cdot \hat{j} + A_x B_z \hat{i} \cdot \hat{k} \\ &+ A_y B_x \hat{j} \cdot \hat{i} + A_y B_y \hat{j} \cdot \hat{j} + A_y B_z \hat{j} \cdot \hat{k} \\ &+ A_z B_x \hat{k} \cdot \hat{i} + A_z B_y \hat{k} \cdot \hat{j} + A_z B_z \hat{k} \cdot \hat{k} \end{aligned}$$

$$\mathbf{A} \cdot \mathbf{B} = A_x B_x + A_y B_y + A_z B_z$$

$$= A_x B_x + A_y B_y + A_z B_z$$